

**BOĞAZIÇI UNIVERSITY**  
**DEPARTMENT OF INDUSTRIAL ENGINEERING**  
**FALL 2015 - 2016**

**IE 440 NONLINEAR MODELS IN OPERATIONS RESEARCH**

Day and Time	: M 13:00 – 15:00	W 13:00 – 14:00
Classroom	: M 3120	M 2230
Instructor	: İ. Kuban Altınel	
Office/Phone	: Old Engineering Building, Ext. 6407	
Office Hours	: M 11:00 – 13:00	W 11:00 – 13:00
Teaching Assistant	: Cemil Dibek	
Office	:	
Office Hours	: TBA	

**Grading**

Quizzes	: 10% per quiz (2 midterm-like quizzes), Close book.
Programs	: 10% (6 programs. The lowest grade will be dropped)
Midterm	: 25%, Close book.
Eligibility	: Any registered student may take the midterm exam.
Makeup	: NO MAKEUP. ABSENCE WILL BE GIVEN 0 WHATEVER THE REASON IS!
Final	: 40%, Close book.
Eligibility	: Only registered students with a 70 overall weighted average or above, if they were given full grade at the final exam, e.g. 100, may enter.
Makeup	: Only registered students who are eligible to take the final will be given a makeup exam if he/she fails the course or he/she is absent at the final exam with an officially accepted excuse.
Attendance	: 5 %

Textbook: There is no textbook.

References: 1. Practical Methods of Optimization, R. Fletcher  
2. Linear and Nonlinear Programming, 2nd edition, D. Luenberger  
3. Introduction to the theory of neural computation, J. Hertz, A. Krogh, R. G. Palmer  
4. Neural Networks in optimization, Z-S Zhang  
5. Past IE 303 and IE 485 exams and their solutions  
**THEY ARE ALL AVAILABLE ON RESERVE AT THE LIBRARY.**

**IE 440 TENTATIVE PLAN**

1. NONLINEAR OPTIMIZATION IN ONE DIRECTION  
Analytical optimization, Iterative optimization, Convergence, Speed of convergence, Search methods, Approximation methods.
2. CONVEXITY  
Convex sets, Convex functions, Gradient, Hessian, Eigenvalues and eigenvectors, Positive definiteness.
3. NONLINEAR UNCONSTRAINED OPTIMIZATION IN MANY DIRECTIONS  
Necessary and sufficient conditions, Search methods (coordinate search, pattern search, simplex search), Descent directions and steepest descent method, Newton's method, Davidon-Fletcher-Powell and Broyden-Fletcher-Goldfarb-Shanno methods.
4. CONSTRAINED NONLINEAR OPTIMIZATION  
Necessary and sufficient conditions, Saddle point problem and its relation with convex programs, Reduced gradient and generalized reduced gradient methods.
5. NEURAL NETWORKS  
Supervised learning and back propagation algorithm, Unsupervised learning and self-organizing maps.
6. MACHINE LEARNING  
Learning as an optimization problem, Discriminant design, Support vector machines.

**IE 440 TENTATIVE PROGRAM**

<u>WEEK</u>	<u>MONTH</u>	<u>DAY</u>	<u>TENTATIVE DAILY OUTLINE</u>
1	September	28M	Nonlinear model examples
		30W	"
2	October	05M	Nonlinear optimization in one variable
		07W	"
3		12M	Convexity
		14W	"
4		19M	Unconstrained nonlinear optimization in many variables
		21W	"
5		26M	"
		28W	"
6	November	02M	Constrained nonlinear optimization in many variables
		04W	"
7		09M	"
		11W	"
8		16M	"
		18W	Neural Networks – Simple Perceptrons
9		23M	"
		25W	Neural Networks – Multi-layer Perceptrons
10	December	30M	"
		02W	Neural Networks – Self-organizing maps
11		07M	"
		09W	"
12		14M	Machine Learning
		16W	"
13		21M	"
		23W	"